

M.Sc. (Electronics) (New CBCS Pattern) Semester - III
PSELT304.2 - SEC2-Paper-IV : Mechatronics

P. Pages : 2

Time : Three Hours



GUG/S/23/11259

Max. Marks : 80

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- Notes :
1. All questions are compulsory and carry equal marks.
 2. Draw well labelled diagrams wherever necessary.
 3. Use of calculator is allowed.

Either:

1. a) What is mechatronics system? Differentiate between traditional and mechatronics design. **8**
- b) What is LVDT? Explain construction and working of LVDT. Draw its characteristics. **8**

OR

- c) Describe static and dynamic characteristics of transducers. **8**
- d) What is control system? Explain the need of control system with suitable example. **8**

Either:

2. a) Explain unit and ramp response of first order. **8**
- b) Describe: **8**
 - i) Natural and forced response
 - ii) Transient and steady state response

OR

- c) Describe the basic model for an electrical system. **8**
- d) Describe the rotational system with basic building block. **8**

Either:

3. a) Discuss the system with negative feedback. **8**
- b) What is Bode Plot? Explain with suitable examples. **8**

OR

- c) What is transfer function? Explain the transfer function of R – C series circuit. **8**
- d) Differentiate between a system with negative and positive feedback. **8**

Either:

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| 4. | a) | Draw the block diagram of digital control system and explain. | 8 |
| | b) | Describe steady state error. How can it be minimized? | 8 |

OR

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|-----------|----|--|----------|
| | c) | Describe PD and PI controllers with suitable diagram. | 8 |
| | d) | State and explain various control modes used in controllers. | 8 |
| 5. | a) | Explain optical encoders in mechatronics. | 4 |
| | b) | Describe the mathematical model of a system. | 4 |
| | c) | Explain location of poles on s - plane. | 4 |
| | d) | Explain self tuning control system. | 4 |
