

M.Sc. (Electronics) (New CBCS Pattern) Semester - III
PSELT304.2 - SEC2-Paper-IV : Mechatronics

P. Pages : 2

Time : Three Hours



GUG/S/23/11259

Max. Marks : 80

- Notes :
1. All questions are compulsory and carry equal marks.
 2. Draw well labelled diagrams wherever necessary.
 3. Use of calculator is allowed.

Either:

1. a) What is mechatronics system? Differentiate between traditional and mechatronics design. **8**
b) What is LVDT? Explain construction and working of LVDT. Draw its characteristics. **8**

OR

- c) Describe static and dynamic characteristics of transducers. **8**
d) What is control system? Explain the need of control system with suitable example. **8**

Either:

2. a) Explain unit and ramp response of first order. **8**
b) Describe: **8**
 - i) Natural and forced response
 - ii) Transient and steady state response

OR

- c) Describe the basic model for an electrical system. **8**
d) Describe the rotational system with basic building block. **8**

Either:

3. a) Discuss the system with negative feedback. **8**
b) What is Bode Plot? Explain with suitable examples. **8**

OR

- c) What is transfer function? Explain the transfer function of R – C series circuit. **8**
d) Differentiate between a system with negative and positive feedback. **8**

Either:

4. a) Draw the block diagram of digital control system and explain. 8
b) Describe steady state error. How can it be minimized? 8

OR

- c) Describe PD and PI controllers with suitable diagram. 8
d) State and explain various control modes used in controllers. 8
5. a) Explain optical encoders in mechatronics. 4
b) Describe the mathematical model of a system. 4
c) Explain location of poles on s - plane. 4
d) Explain self tuning control system. 4
